CERAMIC ARCHITECTURES AS MODELS FOR 3D PRINTED TISSUE

ENGINEERING APPLICATIONS

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Abstract

Shrinkage of ceramic objects produced by Fused Depositon Ceramics 3D printing technology was studied as model procedure for production of biocompatible scaffolds. The formulation of ceramic composite filament tested was based on components such as aluminium and silicium oxides and thermoplastic polymer. The resulting ceramic material after sintering is approaching the chemical composition of the mullite ceramics, which has several interesting material properties. The shrinkage of the produced testing objects was studied as function of the particle content in starting composite and sintering temperature. Observed shrinkage of the ceramic bodies produced was on the level of 17% for 65 weight % and the 23% for 40 weight % of inorganic filler content at temperature 1200 °C, respectively, with well maintained shape. The tested ceramic scaffolds were produced using slice thickness of 0.50 mm and fill gap of 0.58 mm, with regular rectilinear infill pores generated by Slic3r.

Keywords

3D printing, composite materials, ceramic filament, fused deposition of ceramic, mullite, shrinkage

Introduction

Biocompatible scaffolds produced by 3D printing technologies were currently proved to be promising patient-friendly replacements respecting individual specific biological shape individualities and excellent on place availability for the surgery utilization in the future. Their easy on-site availability and production can significantly improve chances of accident and/or arthroplasty joint revision, tumor patients, war zone victims' replacements, for their good and functional recovery and tissue regeneration after surgical operation. The tissue scaffolds for these types of operation are the hard bone replacements based on biocompatible hydroxyapatite (HAp) [1–3].

The low-cost fused deposition ceramics (FDC) technique requires the HAp to be mixed with a 3D-printable thermoplastic and biocompatible polymer such

as polylactic acid (PLA). However, for enhanced bioactivity of the substitute, it is important to produce high HAp-loaded 3D-printable filaments. The known HAp filaments have usually non desired brittle nature at HAp content above 50% of fillings, which is required for good osteoconductive and osteointegration properties. Therefore, an optimized chemical composition and 3D printing processing technology are continually investigated by the researcher teams [4–7].

From these reasons we have investigated a mullite based ceramics prepared from filament with solid content of 40 and 65 weight % as model system for lowcost FDM (Fused Deposition Modeling) technology. It is well known that mullite (3Al₂O₃·2SiO₂) has good chemical and thermal stability, low thermal expansion coefficient, good fracture toughness, bending strength and others properties. In addition, the SiO₂ is a typical component which improves the scaffold biocompatibility along with oxides containing biologically active components such as CaO, Na₂O and/or K_2O [8–11]. Due to the fact that shrinkage of ceramic materials during their firing and sintering is their inherent behavior, the main objective of the presented study was to investigate the effect of temperature and composite filling extend on their ability to produce mullite based ceramic from filaments having new applicable formulations.

Methods

3D Printing Process

The filament having diameter of 1.75 mm was prepared by extrusion of inorganic/organic composite material using single screw extruder. A set of defined green bodies of circular shape with aspect ratio (diameter/height) equal to 5 was printed on commercial FDM 3D printer Leapfrog Creatr™ (Leapfrog 3D printers, Netherlands) with rectilinear infill according to parameters as shown in the Fig. 1. Estimated green body road width (RW) was about 0.67 ± 0.02 mm and infill road gap (RG) about 0.58 ± 0.02 mm produced after default extrusion using Slic3r (open-source software, Slic3r.org) set on infill density at the level of 35%, using the nozzle diameter 0.6 mm. The nozzle temperature (NT) was set to 215 °C, 1st road height (1RH) to 0.75 mm while the slice height of the following roads (RH) was set to 0.70 mm. The temperature of heated bed (HB) was set to 55 °C (Fig. 1).

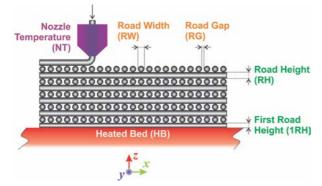


Fig. 1: FDC printed rectilinear infill cross-section viewed in the XZ plane of the 3D building process (parameters directly selected by the operator: 1RH, RH, HB, NT and inherently achievable values: RW, RG).

It must be emphasized that only selected printing parameters such as 1RH and subsequent RH's are common adjustable parameter in Slic3r or similar software for FDM 3D printers available. The RW depends intrinsically on nozzle diameter, extrusion velocity and inherently includes polymer expansion coefficient. It is as well inversely proportional to value entered for RH. For the biocompatible scaffolds production it is essential achievement of bimodal pore size distribution. Such distribution should mimic pore sizes in real bones, where average pore diameters at the level of mesopores, hence below 50 nm and macropores, above 100 μ m can be found. From these dimension values it is clear, that an empirical estimation of RW and RG based on selection of infill density must be experimentally verified to produce the pores with diameter ~100 μ m. However, the pore sizes ~50 nm can be achieved by the selection of appropriate inorganic biocompatible material only, such as HAp with sufficiently suitable internal pore structure [12,13].

Experimental

3D printed green bodies were subjected to de-binding process in laboratory furnace ClasicTM 1013 (Clasic a.s., Czech Republic), allowing programming complex heat ramp for desired heating mode. The Table 1 summarizes the temperature programs used for object debinding and sintering. The heat ramp for debinding process included was performed under slow and fast debinding modes: i) the temperature change from room temperature (RT) \rightarrow 850 °C in 69.5 hours; ii) accelerated debinding from room temperature (RT) \rightarrow 850 °C in 4.38 hours. The final sintering temperatures were set to 1200 °C, 1300 °C, and 1400 °C.

Table 1: Temperatures and time required for green body debinding and object sintering used for 1 hour.

Temperature program (°C)	Required Time (h)	Sintering at temperature (°C)
$RT \rightarrow 850^{i)}$	69.5	-
$RT \rightarrow 850^{ii)}$	4.38	_
$RT \rightarrow 1200$	3.92	1200
RT ightarrow 1300	4.25	1300
RT ightarrow 1400	4.58	1400

i) slow debinding mode; ii) fast debinding mode.

To investigate the road merging during printing and sufficiency of material coalescence in sintering process, cut segments of 3D printed bodies were inspected by scanning electron microscopy (SEM). Well merged connections of material roads are important to achieve material strength required. This investigation was done for filament filled with 65 weight % and heated to temperature 1200 °C for accelerated debinding mode. No shape-stable brown bodies were produced from filament filled with 40 weight % if the accelerated debinding mode was used.

The imaging of prepared green/brown/sintered bodies was done in accordance to magnification required, e.g. for simple printed body visualization and data archives a common camera images with resolution up to 20 MP were photographed. Magnified images for inspection of macropores were collected using optical microscope Zeiss Stemi 508. This was equipped with objective set enabling enlargements ranging from 0.63 to $5\times$ and coupled with Axiocam 105 (Carl Zeiss AG, Germany) color camera. For inspection of mesopores SEM images of the sintered material species were recorded by a JEOL JEM-2000FX (JEOL Ltd., Tokyo, Japan) with an accelerating voltage of 160 kV.

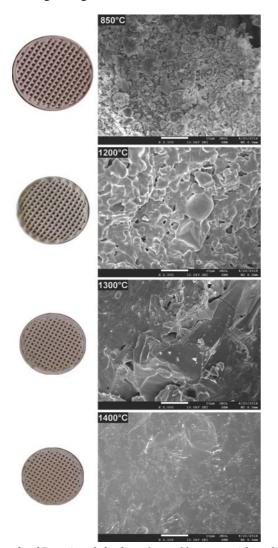


Fig. 2: 3D printed bodies from filament with solid content of 40 weight %, resulting size after debinding at 850 °C and sintering at 1200 °C, 1300 °C, 1400 °C (top to bottom left), corresponding material microstructure on SEM images (top to bottom right).

Results

The comparison of 3D printed green body microstructure and respective body shapes achieved from filament filled with 40 weight % and debinded in slow mode are shown in the Fig. 2. In dependence on final temperature of thermal treatment (Table 1) different surface morphology and final body shrinkage can be observed. The material merging on intercrossing sections made of filament filled with 65 weight %, debinded in fast rates and sintered at temperature 1200 °C are shown on the SEM images (Fig. 3). Single roads of crossed material can be clearly identified on the images, while magnified images show the size of several pores at the level of less than $150 \,\mu$ m.

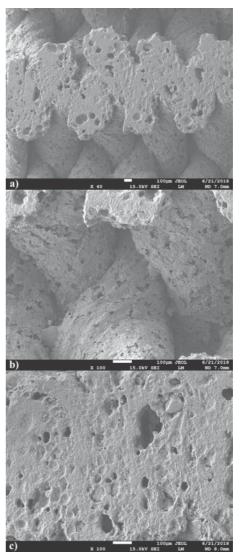


Fig. 3: material merging a) roads cross-sections b) and merged pores morphology c) in 3D printed bodies debinded by fast mode.

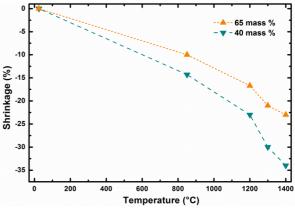


Fig. 4: Shrinkage dependence of 3D printed bodies as function of temperature and solid content.

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In the first stage of our study, the investigation of total green body shrinkage during thermal treatment was done. Fig. 4 shows the comparison of object diameter linear shrinkage as function of debinding and sintering temperatures and ceramic pre-cursor mixture solid content. Gradual acceleration of shrinkage as temperature function can be clearly identified. This indicates that processes with two rates were taking place during composite heating and differed mainly in debinding and sintering heating phases.

Discussion

The 3D printed model object debinded at 850 °C shown in Fig. 2 indicates presence of individual particles used as pre-cursor and source of aluminum oxide and silicon dioxide. Microstructure images for 1200 and 1300 °C indicate gradual reduction of the porosity resulting from the brown body structure. There is clearly observable fracture line in the right top corner of sample sintered at 1300 °C. However, the origin of this fracture is probably to be connected with sample preparation for SEM measurements, as no such fractures are to be found in the macro images corresponding to 1200 and 1400 °C. At sintering temperature of 1400 °C, only glassy surface of the ceramic objects produced from liquid phase present at this temperature can be observed. This indicates that if defined porosity for biologically applicable scaffolds is required, the sintering must be performed below temperatures where complete porosity closing is reached.

The cross sections of sample sintered to 1200 °C cut by diamond cutter shown on SEM images (Fig. 3a) demonstrate excellent material merging and homogeneous cross-section of the roads. Nevertheless, enlargement of joint material parts only does not offer clear evaluation of material merging after 3D printing and sintering (Fig. 3b). It is noteworthy, that pores observed on material sintered at temperature 1200 °C revealed presence of oval pores with sizes smaller than 150 μ m required for natural bone structure mimicking. Some pores seem to be interconnected, what is essential if good level of biocompatibility of material is required (Fig. 3c) [6].

Presented results show clearly the importance of correct adjustment of several control parameters to achieve required scaffolds properties if produced by 3D printing techniques [14]. The object diameter linear shrinkage as function of debinding and sintering temperature and ceramic pre-cursor mixture solid content at the level of 40 and 65 weight % is shown in the Fig. 4. The dependence comparison noticeably indicates two stages in green body shrinkage rates during thermal treatment: i) at long debinding times, the change of shrinkage has linear dependence with the slope affected by the solid content level; ii) from certain temperature, at which the sintering of particle starts for

short sintering times, the shrinkage is accelerated by increasing sintering temperature (Fig. 3). Let us define the debinding specific shrinkage rate (SR_S) as change of object linear dimension change, such as diameter, divided by the time required and temperature gradient causing the change observed, by formula (1).

$$SR_S = \frac{d^2 \Delta l}{d\tau \cdot dt} \tag{1}$$

The Δl represents the object linear size change in μm which was induced in time interval $d\tau$ in hours and was caused by temperature change dt in °C for the temperature interval RT \rightarrow 850 °C and slow debinding mode. Combining the shrinkage values from Fig. 2, the time required to induce the change caused by temperature change as shown in the Table 1, we can obtain used debinding specific shrinkage rates. The bodies prepared from 40 weight % filled filament have *SRs* at the level of 0.087 μ m·hour^{-1.}°C⁻¹. Increase of the filling solid content from 40 to 65 weight % decreased the SR_s value for about the half, at the level of 0.044 μ m·hour^{-1.o}C⁻¹. The debinding process is one of the most critical manufacturing steps due to its significant influence on density, shape, strength and final quality of ceramic parts produced by FDC.

After debinding and their size determination were the brown bodies heated towards sintering temperature from RT by heating rate equal 5 °C per minute. In such case higher specific shrinkage rates were observed for sintering of bodies prepared from filaments having higher weight content of reacting particles. For example, higher specific shrinkage rates were found for sintering of brown bodies prepared from filament with lower solid content. *SRs* for heating 850 \rightarrow 1400 °C and 40 weight % filament at the level of 6.942 µm·hour^{-1.°}C⁻¹, while *SRs* 5.504 µm·hour^{-1.°}C⁻¹ was found for 65 weight % filament. This can be seen indicative for more intensive interactions and chemical reactions between particles during ceramic body sintering from filaments with higher filling content by solid particles.

Conclusions

The ceramic bodies as model objects for hard tissue replacements were prepared by FDM technology from new type of filament producing mullite type ceramics. Specific conditions for 3D production of sintered FDC parts showed favorable merging and interconnection of material roads ensuring future mechanical strength required. At the same time the porosity observed with pores < 150 μ m mimics well the transport pores in real bones. As expected, it was found that overall shrinkage rates during printed body debinding and sintering are higher in case where filament with lower filling amount of ceramic pre-cursor particles was used. The debinding process is one of the most critical manufacturing steps

due to its significant influence on final quality of ceramic parts produced by FDC. Specific debinding shrinkage rate for slow debinding process was higher for filaments with lower filling grade. Similarly, higher specific shrinkage rate was found for brown bodies sintered in the temperature range $850 \rightarrow 1400$ °C, due to the fact that higher amount of organic binder is present in filament with lower filling grade.

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